Geometry and quantum control

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Geometry of Quantum Mechanics in complex projective spaces

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With the support of:



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Geometrization of Quantum Mechanics

Describing quantum systems in terms of geometric structures.

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Geometrization of Quantum Mechanics

Describing quantum systems in terms of **geometric structures**. Why?

- Standard formulation of Quantum Mechanics presents a mathematical structure that is linear and algebraic (operators in Hilbert spaces)
- Classical Mechanics can be mathematically formulated in a broad and elegant differential geometric framework (symplectic manifolds, Hamiltonian fields, Poisson structures...).

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Phylosophical goal: A unified quantum/classical geometric scenario!

Technical goal: Application of powerful geometric tools that are well-known in Classical Mechanics to quantum problems.

Geometrization of Quantum Mechanics

Some landmarks

- T. W. B. Kibble Geometrization of quantum mechanics, Comm. Math. Phys. 65 (1979)
- A. Ashtekar and T. A. Schilling *Geometry of quantum mechanics*, AIP Conf. Proc. 342 (1995)
- D.C. Brody and L.P. Hughston Geometric quantum mechanics, J. Geom. Phys. 38 (2001)
- J. Clemente-Gallardo and G. Marmo Basics of quantum mechanics, geometrization and some applications to quantum information, Int. J. Geom. Methods Mod. Phys. 5(6) (2008)

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Summary

Geometric Hamiltonian formulation of QM

Quantum Mechanics in a classical-like fashion From operators to phase space functions

Geometry and quantum control

Notions of quantum controllability Differential geometry and quantum controllability

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Classical tools

Phase space

A classical system with *n* spatial degrees of freedom is described in a 2*n*-dimensional symplectic manifold (\mathcal{M}, ω) .

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Physical state A point $x = (q^1, ..., q^n, p_1, ..., p_n)$

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Dynamics

A curve in $(a, b) \ni t \mapsto x(t) \in \mathcal{M}$ satisfying Hamilton equations:

$$\frac{dx}{dt} = X_H(x(t))$$

 $H: \mathcal{M} \to \mathbb{R}$ is the Hamiltonian function. X_H is the Hamiltonian vector field, given by: $\omega_x(X_H, \cdot) = dH_x(\cdot)$

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Classical tools

Statistical description

The state is a ${\mathfrak C}^1\text{-}{\rm function}\ \rho$ on ${\mathcal M}$ and dynamics is described by the Liouville equation

$$\frac{\partial \rho}{\partial t} + \{\rho, H\}_{PB} = 0$$

Poisson bracket: $\{f,g\}_{PB} := \omega(X_f, X_g)$.

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Physical quantities are real smooth function on \mathcal{M} : The Observable *C**-algebra is:

$$\mathcal{A}=\mathfrak{C}^\infty(\mathfrak{M})$$

Classical expecation value of $f : \mathcal{M} \to \mathbb{R}$ on ρ :

$$\langle f \rangle_{\rho} = \int_{\mathcal{M}} f(x) \rho(x) d\mu(x)$$

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QM in a classical-like fashion

Standard formulation of QM in a Hilbert space \mathcal{H} :

Quantum states: $D(\mathcal{H}) = \{ \sigma \in \mathfrak{B}_1(\mathcal{H}) | \sigma \ge 0, tr(\sigma) = 1 \}$ Quantum observables: Self-adjoint operators in \mathcal{H} .

Pure states (extreme points of the convex set D) are in bijective correspondence with projective rays in \mathcal{H} :

$$\mathcal{P}(\mathcal{H}) = \frac{\mathcal{H}}{\sim} \qquad \psi \sim \phi \iff \exists \alpha \in \mathbb{C} \setminus \{\mathbf{0}\} \ s.t. \ \psi = \alpha \phi$$

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 $\dim \mathcal{H} = n < +\infty$

 $\mathcal{P}(\mathcal{H})$ is a real (2n-2)-dimensional manifold with the following characterization of tangent space:

$$\rho \in \mathcal{P}(\mathcal{H})$$
: $\forall v \in T_{\rho}\mathcal{P}(\mathcal{H}) \exists A_{v} \in \mathfrak{H}(\mathcal{H}) \text{ s.t. } v = -i[A_{v}, \rho].$

 $\mathfrak{H}(\mathcal{H})$ is the space of hermitian operators on \mathcal{H} .

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$\mathcal{P}(\mathcal{H})$ as a Kähler manifold

Symplectic form: $\omega_p(u, v) := -i k tr([A_u, A_v]p)$ k > 0Riemannian metric:

$$g_{\rho}(u,v) := -k tr(([A_u, \rho][A_v, \rho] + [A_v, \rho][A_u, \rho])\rho) \qquad k > 0$$

Almost complex form: $j_p : T_p \mathcal{P}(\mathcal{H}) \ni v \mapsto i[v, p] \in T_p \mathcal{P}(\mathcal{H})$ $p \mapsto j_p$ is smooth and $j_p j_p = -id$ for any $p \in \mathcal{P}(\mathcal{H})$:

$$\omega_p(u,v) = g_p(u,j_pv)$$

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Quantum observables as phase space functions $\mathcal{O}: \mathfrak{H}(\mathcal{H}) \ni A \mapsto f_A: \mathcal{P}(\mathcal{H}) \to \mathbb{R}$

Equivalence Hamilton/Schrödinger dynamics:

$$\frac{dp}{dt} = -i[H, p(t)] \quad \Leftrightarrow \quad \frac{dp}{dt} = X_{f_H}(p(t))$$

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Quantum states as Liouville densities $\mathcal{S}: D(\mathcal{H}) \ni \sigma \mapsto \rho_{\sigma}: \mathcal{P}(\mathcal{H}) \to [0, 1]$

Equivalence quantum/classical expectation values:

$$\langle A \rangle_{\rho} = \operatorname{tr}(A\sigma) = \int_{\mathcal{M}} f_{A}(p) \rho_{\sigma}(p) d\mu(p)$$

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From operators to functions

Definition

A map $f : \mathcal{P}(\mathcal{H}) \to \mathbb{C}$ is called **frame function** if there is $W_f \in \mathbb{C}$ s.t.

$$\sum_{p\in N} f(p) = W_f$$

for any $N \subset \mathcal{P}(\mathcal{H})$ s.t. $d_g(p_1, p_2) = \frac{\pi}{2}$ for $p_1, p_2 \in \mathcal{P}(\mathcal{H})$ with $p_1 \neq p_2$ and N is maximal w.r.t. this property.

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$$\mathfrak{F}^{2}(\mathfrak{H}):=\{f:\mathfrak{P}(\mathfrak{H})\rightarrow\mathbb{C}|\,f\in\mathcal{L}^{2}(\mathfrak{P}(\mathfrak{H}),\mu),\,\,f\,\text{is a frame function}\}$$

Theorem (V. Moretti, D.P. 2014)

Phase space functions describing quantum observables are real functions in $\mathfrak{F}^2(\mathfrak{H})$ and obtained from operators by:

$$\mathfrak{O}:\mathfrak{H}(\mathfrak{H})\ni A\mapsto f_A \qquad f_A(p)=k\ tr(Ap)+\frac{1-k}{n}\ tr(A) \quad k>0$$

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Theorem (Ashtekar et al. 1995)

A vector field X on $\mathcal{P}(\mathcal{H})$ is the Hamiltonian vector field of a quantum observable (i.e. X(p) = -i[A, p] with $A \in \mathfrak{H}(\mathcal{H})$) if and only if

$$\mathcal{L}_X g = 0$$

C*-algebra of quantum observables in terms of functions

$$\begin{array}{ll} \bigcirc: \mathfrak{H}(\mathcal{H}) \ni A \mapsto f_A & - \text{ linear extension} \to & \bigcirc: \mathfrak{B}(\mathcal{H}) \to \mathcal{F}^2(\mathcal{H}) \\ \mathcal{F}^2(\mathcal{H}) \text{ as C*-algebra of observables} \\ -) \text{ Involution: } A = \bigcirc(f), \ A^* = \bigcirc(\overline{f}); \\ -) \star \text{ - product: } f \star g = \bigcirc(\bigcirc^{-1}(f)\bigcirc^{-1}(g)): \\ f \star h = \frac{i}{2}\{f, h\}_{PB} + \frac{1}{2}G(df, dh) + f \cdot h \qquad k = 1 \\ -) \text{ Norm: } |||f||| = || \bigcirc^{-1}(f) || \\ |||f||| = \frac{1}{k} \left| \left| f - \frac{1-k}{n} \int_{\mathcal{P}(\mathcal{H})} f \ d\mu \right| \right|_{\infty} \qquad k > 0 \end{array}$$

where $d\mu$ is the volume form induced by g.

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Quantum control

Controlled *n*-level quantum system

$$i\hbar rac{d}{dt}|\psi
angle = \left[H_0 + \sum_{i=1}^m H_i u_i(t)
ight]|\psi(t)
angle \qquad (*)$$

with initial condition $|\psi(0)\rangle = |\psi_0\rangle$.

Pure state controllability

The *n*-level system is **pure state controllable** if for every pair $|\psi_0\rangle, |\psi_1\rangle \in \mathcal{H}$ there exists controls $u_1, ..., u_m$ and T > 0 such that the solution $|\psi\rangle$ of (*) satisfies

$$|\psi(T)\rangle = |\psi_1\rangle$$

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Quantum control

Controlled *n*-level quantum system

$$i\hbar \frac{d}{dt}U(t) = \left[H_0 + \sum_{i=1}^m H_i u_i(t)\right]U(t)$$
 (**)

with initial condition $U(0) = \mathbb{I}$.

Complete controllability

The *n*-level system is **complete controllable** if for any unitary operator $U_f \in U(n)$ there exist controls $u_1, ..., u_n$ and T > 0 such that the solution U of (**) satisfies

$$U(T) = U_f$$

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Differential geometry and quantum controllability

Geometric Hamiltonian formulation

$$\dot{p}(t) = X_0(p(t)) + \sum_{i=1}^m X_i(p(t))u_i(t)$$

 X_i are the Hamiltonian fields on $\mathcal{P}(\mathcal{H})$ defined by the classical-like Hamiltonians obtained with our prescription.

Accessibility algebra

The smallest Lie subalgebra \mathcal{C} of the Lie algebra of smooth vector fields on $\mathcal{P}(\mathcal{H})$ containing the fields $X_0, ..., X_m$.

Accessibility distribution

$$\mathfrak{C}(p) := \operatorname{span}\{X(p) \,|\, X \in \mathfrak{C}\}$$

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Theorem (D.P. 2016)

A quantum system is pure state controllable if and only if the following condition is satisfied:

$$T_p \mathcal{P}(\mathcal{H}) = span\{X(p)|X \in \mathcal{C}\}$$

for some $p \in \mathcal{P}(\mathcal{H})$.

The proof is based on this proposition:

$$A \in \mathcal{L} \quad \Longleftrightarrow \quad X_{f_{-iA}} \in \mathcal{C}$$

where \mathcal{L} is the Lie algebra generated by $-iH_0, ..., -iH_1$.

Corollary

A quantum system is completely controllable if and only if

$$\mathcal{C} = \mathfrak{Kill}(\mathcal{P}(\mathcal{H}))$$

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An example

Consider a controlled 4-level quantum system whose dynamical Lie algebra \mathcal{L} is given by the matrices of the form:

$$A = \begin{pmatrix} -ia & c & z & d \\ e & ib & f & w \\ -\overline{z} & d & ia & e \\ f & -\overline{w} & c & -ib \end{pmatrix},$$

where $a, b, c, d, e, f \in \mathbb{R}$ and $z, w \in \mathbb{C}$.

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where $a, b, c, d, e, f \in \mathbb{R}$ and $z, w \in \mathbb{C}$. Let p = diag(1, 0, 0, 0) and calculate:

$$X_{\mathcal{A}}(p) = \begin{pmatrix} 0 & -c & -z & -d \\ e & 0 & 0 & 0 \\ -\overline{z} & 0 & 0 & 0 \\ f & 0 & 0 & 0 \end{pmatrix},$$

dim $\mathcal{C}(p) = 6 = \dim T_p \mathcal{P}(\mathcal{H})$. Pure state controllability!

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